



1 **Joint Authorities for Rulemaking of Unmanned Systems**

## **Module - FLIGHT AREA PDRA 02 to complement the BASIC Operations Manual:**

- **Generic,**
- **Lightly populated area,**
- **segregated or reserved airspace,**
- **containment (low)**

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3  
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## 20 1. Introduction

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21 This module is intended to complement the Basic Operations Manual. It gives an example on how to present a flight  
22 area in accordance to annex A.

23 The operator has to ensure that the flight areas are reflecting his planed locations for his operation.

24 The flight area should be adjusted to reflect the actual UAS operation, however significant care should be directed to  
25 the mutual dependency of SORA risk assessment and comprehensive safety portfolio (compliance matrix). For example,  
26 a higher Flight Altitude (FG) might be possible in the flight area as long as the Operational Volume is completely within  
27 the segregated or reserved airspace. The calculations have to be adjusted to reflect this altitude.

28 The competent authority will review the resulting description of the FLIGHT AREA in the process of reviewing the  
29 application in accordance with the provisions arising from the risk assessment and the respective SAIL. In this process,  
30 the implementation of all technical and operational requirements is checked based on the descriptions in the operations  
31 manual, or other associated documents as required. The competent authority has the option to request revisions of  
32 documents or to ask for additional supporting documentation.

33

## 34 2. Scope of Module - Flight Area PDRA 02

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35

36 (a) Scope

37

38 This module provides an example for – FLIGHT AREA PDRA 02:

- 39 • Generic nature,
- 40 • Lightly populated area,
- 41 • Segregated or reserved airspace for the operation and
- 42 • Low containment

43

44

45 (b) Module characterisation and conditions

46

47 The characterisation and conditions for this module are summarised in section 3.

48

### 49 3. Flight Area

50 G

#### 51 In section 2.7.1.3

52 replace action RPIC

- 53 • Check Ground area
- 54 • Check Airspace

55 with

- 56 • Check controlled ground established
- 57 • Check airspace reserved for the operation is established

58

59 G

60

#### 60 In Chapter C, 3.2

61 please add a section for the flight area

### 62 3.2 Flight Area (PDRA 02)

#### 63 3.2.1 Description

64 The following flight area is a generic one in **Country**.

65 In order to conduct flight operations in a certain area, the following conditions apply beyond the general  
66 operating limits.

67 The maximum flight altitude ( $H_{FG}$ ) is 120 m AGL (above ground level) at all times and may only be exceeded  
68 within a horizontal distance of 50 m from an artificial obstacle taller than 105 metres. The maximum height  
69 of the UAS operation may then be increased up to 15 m above the height of the obstacle at the request of  
70 the entity responsible for the obstacle.

71 The adjacent area is calculated from the CV as follows

72  $S_{AV} = 180 \text{ s} * \text{operating speed [m/s]} = 180 \text{ s} * 35 \text{ m/s} = 6300 \text{ m}$  (values from 3.1.2)

73

#### 74 3.2.2 Ground risk:

75 The UAS may only be operated such that the operating volume (FG and CV) and the ground risk buffer as a  
76 whole are classified as a LIGHTLY POPULATED AREA (< 50 people/km<sup>2</sup>).

77 This includes for example areas of small farms. Residential areas with very large lots (~ 4 acres or 16,000 m<sup>2</sup>).

78 It has to be assured before commencing flight operation that the ADJACENT AREA does not have an average  
79 population density above 5000 ppl/km<sup>2</sup> (sheltered environment) nor contain assemblies of people above 40k  
80 people.

- 81 • *Please specify which data source has been used to assess the population density (e.g. global human  
82 settlement layer Epoch YYYY).*

83

84 3.2.3 Air risk:

85 Flight operations may only be conducted in a segregated or reserved airspace, with an initial risk class of ARC-  
86 a.

87 This is achieved by:

- 88 • *Please specify how this is done, e.g. restricted airspace for the operation, or part of a controlled*  
89 *airspace where separation is guaranteed by ATC.*

90 Compliance with these criteria is checked on a daily basis.

91

92 3.2.4 Documentation

93 For each flight location to be flown, a kml file must be created with the values for CV, GRB listed here.

94 The flight locations are recorded in the Flight-Log.

95 The flight location and the unique name of the kml file have to be entered in the field “flight area”.

96 All data (kml file and Flight-Log) must be available for an audit at any time.

97

98 3.2.5 Calculation of CV / GRB  
99 The calculation of the contingency volumes and of the ground risk buffer is based on the “Guidelines on  
100 collecting and presenting system and operation information for a specific UAS operation” (Annex A).  
101 This explicit calculation was performed using the “map tool” of the Digital Platform for Unmanned Aviation  
102 (dipul), version 1.0.  
103  
104 3.2.5.1 *Input values used for the calculation of CV/GRB*  
105  
106 UAS characteristics:  
107 • Type: Rotorcraft with parachute  
108 • Type of altimetry: Barometric  
109 • Maximum speed  $v_0$ : 5.0 m/s  
110 • Maximum wind speed allowed  $v_{Wind}$ : 5.0 m/s  
111 • Characteristic Dimension: < 3.0 m  
112 • Maximum pitch angle  $\theta_{max}$ : 30.0 °  
113 • Parachute opening time  $t_{parachute}$ : 2.0 s  
114 • Descent rate with parachute  $v_z$ : 2.0 m/s  
115  
116 The following parameters were used:  
117 • Height of flight geography  $H_{FG}$ : 120.0 m  
118 • Horizontal contingency volume manoeuvre: stopping  
119 • Vertical contingency manoeuvre: kinetic into potential energy  
120 • Ground risk buffer manoeuvre: Parachute  
121  
122 Assumptions  
123 • GPS inaccuracy  $S_{GPS}$ : 3.0 m  
124 • Position holding error  $S_{POS}$ : 3.0 m  
125 • Map error  $S_K$ : 1.0 m  
126 • Reaction time  $t_{Reak}$ : 1.0 s  
127 • Altitude error (barometric)  $H_{Baro}$ : 1.0 m  
128

129 3.2.5.2 Calculation contingency volume

130 Lateral:

131  $S_{RZ} = 5m$

132  $S_{CM} = 2,2m$  (stopping the UAS with maximum pitch)

133  $S_{CV} = S_{GPS} + S_{Pos} + S_K + S_{RZ} + S_{CM} = 14,2m$

134  $S_{CV} = 14,2m$

135

136 Vertical:

137  $H_{RZ} = 3,5m$

138  $H_{CM} = 1,3m$  (kinetic to potential energy)

139  $H_{CV} = H_{FG} + H_{baro} + H_{RZ} + H_{CM} = 125,8m$

140  $H_{CV} = 125,8m$

141

142 3.2.5.3 Calculation ground risk buffer with parachute:

143  $t = 2s$  (time parachute to open)

144  $V_{Wind} = 5 \frac{m}{s}$

145  $V_z = 5 \frac{m}{s}$

146  $S_{GRB} = V_0 * t + V_{Wind} \frac{H_{CV}}{V_z} = 324,4m$

147  $S_{GRB} = 324,4m$

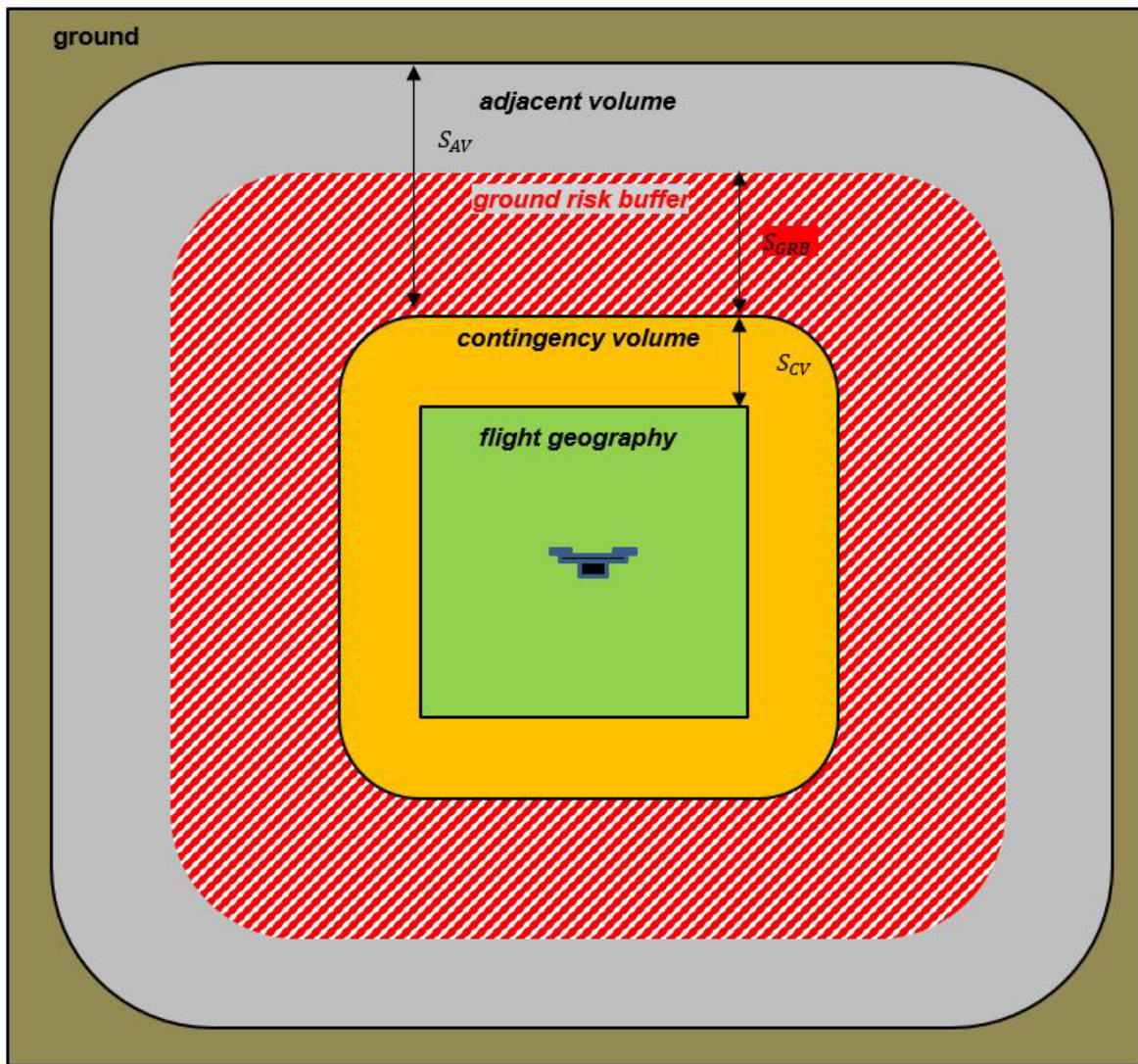
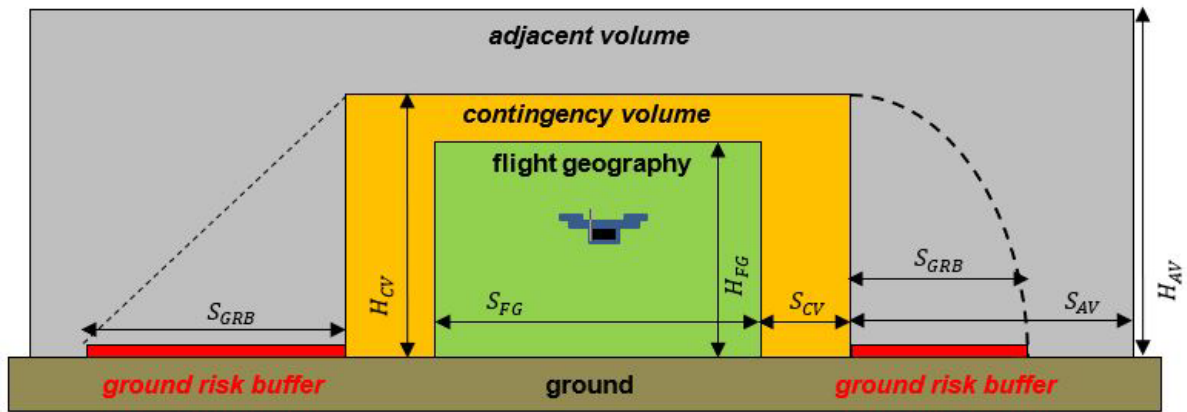
148

149 3.2.5.4 Results of the CV/GRB calculation

150

- 151 • Horizontal contingency volume  $S_{CV}$ : 14.2 m
- 152 • Vertical contingency volume  $H_{CV}$ : 125.8 m
- 153 • Ground risk buffer calculation  $S_{GRB}$ : 324.4 m
- 154 • Height of flight geography  $H_{FG}$ : 120.0 m

155



156

157

Figure 1: Simplified presentation of flight geography, contingency volume and ground risk buffer

158 3.2.6 Specific Procedures of the Flight Area

159 3.2.6.1 *Controlled Ground*

- 160 • Not necessary as unused

161 3.2.6.2 *M1 Mitigation*

162 *(Please refer to the appropriate module to include this mitigation)*

163 3.2.6.3 *ARC-Mitigation*

- 164 • Not necessary as unused

165 3.2.6.4 *Information to Third Parties*

166 In case third parties are affected by the operation, all necessary information will be provided in advance to  
167 all persons concerned and relevant authorisations will be obtained if needed.

168



169	3.2.7 Emergency Response Plan (ERP) - Local Information	
170	Instructions and completion aids for the ERP template (see 8.3.1)	
171		
172	Air traffic controllers possibly affected (ATM)	
173	• Bremen	+49(0)1234 xxxxxxxx
174	• Langen	+49(0)1234 xxxxxxxx
175	• München	+49(0)1234 xxxxxxxx
176		
177	Nearest emergency services:	
178	• Fire/Police/EMS	112
179		